

# Radiometric Calibration Techniques for Signal-of-Opportunity Reflectometers



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Transmitted electric field field as quasi-monochromatic phasor

$$E_t(t, R) = \hat{P}_t \left( \frac{P_t G_t}{4\pi} \right)^{1/2} \frac{e^{-jkR}}{R} a(t - R/c) e^{j2\pi f_p t}$$

Fris loss

Doppler shift referenced to observer

## MOTIVATION

- Internal Calibration
  - Stabilizes receiver gains and offsets
  - Measures correlation efficiency
  - Defeats fluctuations with rapid and periodic updates
- Electronic Calibration Sources
  - Reference switch
  - Common noise source
  - Applicable to general SoOp reflectometers, e.g. [2].
- Similar to Conventional Microwave Instruments
  - L-band radiometer and scatterometers (e.g., [3]-[4])
  - Reference switches, noise diodes and loop-back circuits

## METHODOLOGY

- Reference switching
  - Overcome thermal and  $1/f$  fluctuations
  - Allows removal of receiver noise offset
  - Useful for low SNR direct antenna configurations
- Noise source firing
  - Allows measurement of receiver gains and correlation efficiency
  - Cross-power appears at zero delay
  - Simultaneously observe reflected cross-power when delay difference is much larger than coherence time of signal

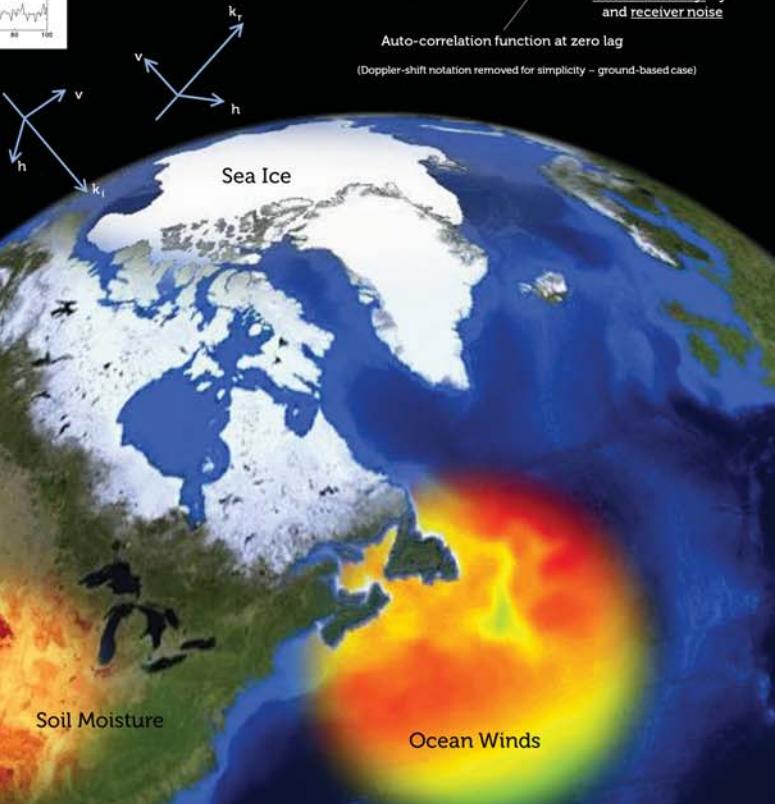
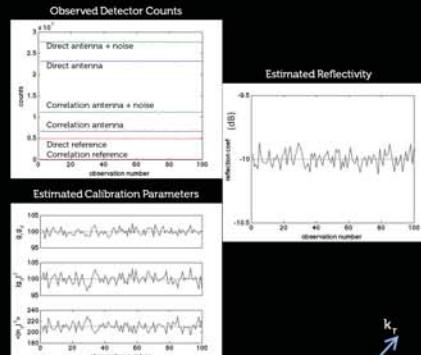
## ABSTRACT

Bi-static reflection measurements utilizing global navigation satellite service (GNSS) or other signals of opportunity (SoOp) can be used to sense ocean and terrestrial surface properties. End-to-end calibration of GNSS-R has been performed using well-characterized reflection surface (e.g., water), direct path antenna, and receiver gain characterization [1].

Here, we propose an augmented approach using on-board receiver electronics for radiometric calibration.

Using similar techniques long-term (days to weeks) calibration stability of the L-band scatterometer and radiometer on Aquarius/SAC-D has been achieved better than 0.1% [5]. Similar long-term stability would likely be needed for a spaceborne reflectometer mission to measure terrestrial properties such as soil moisture.

## SIMULATION RESULTS



## REFERENCES

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